

Autopilot Installation

Installation of Main Computer Unit (MCU)

Position

The **MCU** should be mounted in an accessible position, protected from rain or salt water. Inside a locker or on a bulkhead below decks are suitable. It should be mounted close to the steering motor where convenient to minimise voltage drop between the **MCU** and motor.

Wiring

Access for wiring must be provided. Cabling from the various ancillaries (remote, compass, rfus and autopilot drive motor) will have to be run to the **MCU**. Wiring should be kept as far as possible from radio aerials and aerial cables to prevent interference to the radio, and to prevent transmitted signals from the radio influencing the pilot.

The **MCU** must have a direct connection to power supply via an isolating switch. A power cable rated at 15 amps should be connected between power input switch and terminals on the **MCU**.

Accessibility

The **MCU** location should be easily accessible so that it is possible for a technician to make adjustments to the unit. To access the internal of the unit two screws either end allow the top lid to be removed.

DIP Switch Setting

The DIP switch is located on the PCB near the internal piezo alarm.

1	On	=	RFUS	1	Off	=	RFUH
2	On	=	RFUS	2	Off	=	RFUH
3	On	=	CTS	2	Off	=	Fluxgate
4	On	=	CTS	2	Off	=	Fluxgate